

77ASC026A

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1.0 SCOPE

This test procedure details the system checks, tests, and measurement to insure proper installation and performance of the FBIS Servo Control Systems. These tests are specifically designed to verify proper unit interconnections and to ascertain system performance levels not possible during factory tests. All data and notes recorded during the test performance are to be considered a portion of the test procedure and are attached hereto.

2.0 REFERENCE DOCUMENTS

ESI System Interface Specification 84-08002-000.

3.0 REQUIREMENTS3.1 GENERAL

The tests prescribed herein shall govern the acceptance of the FBIS Servo Control System with respect to performance of the drive systems, control and display functions, system interlocks and fault functions, antenna movement range and dynamic performance, including velocity and acceleration.

3.2 TEST METHODS

The test methods and system configurations prescribed herein shall be mandatory in the conduction of the tests except for those cases in which special conditions existing at the time of test dictate certain modifications or changes. In these circumstances, full documentation of the condition and nature of the changes shall be provided and recorded on the test data sheets.

3.3 TEST CONDITIONS

- a. It is assumed that all antenna mechanical tests and alignments have been completed.
- b. Prior to this test, the antenna position readout will have been checked and aligned.

3.4 TEST EQUIPMENT REQUIRED

- a. Chart Recorder - Brush, Model 220 or equivalent
- b. Function Generator - Wavetek Model 110 or equivalent
- c. ESI Position Test Set

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4.0 DETAILED TEST4.1 FAULT STATUS REPORTING

Set all circuit breakers on and close all interlock switches on the antenna. Apply power to the ACU.

Unit power on in STANDBY Mode. Disable MONITOR if it is on. _____(CHECK)

4.1.1 Individual Fault Status

Open each circuit breaker and interlock switch listed on Table I individually. Note that the status message displayed on the ACU and axis disable agrees with Table 1. Those with an * in the alarm column should cause the alarm lamp on the ACU to flash red. Place ACU in MAN POS mode, zero command, for all checks. Thermostats and phase loss faults may be tested by removing connections in junction boxes, or at drive cabinet. Reclose or reconnect each circuit before next test.

4.1.2 Multiple Fault Status

4.1.2.1 Activate any alarm condition. _____(CHECK)

Press the ALARM switch on the ACU. _____(CHECK)

ALARM switch changes to solid yellow. _____(CHECK)

4.1.2.2 Activate another alarm condition. _____(CHECK)

ALARM switch reverts to flashing red. _____(CHECK)

Asterisk in message display and messages alternate. _____(CHECK)

4.1.2.3 Press the ALARM switch.

ALARM switch is yellow. _____(CHECK)

Messages alternate. _____(CHECK)

4.1.2.4 Remove one alarm.

ALARM switch is yellow. _____(CHECK)

Asterisk not present. _____(CHECK)

4.1.2.5 Remove last alarm.

ALARM switch is off. _____(CHECK)

Data section of display is blank. _____(CHECK)

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TABLE I: SYSTEM AND AXIS FAULT STATUS

SWITCH	MESSAGE	ALARM	AZ	AXIS DISABLED	CHECK
				EL	
AZ #1 EMERGENCY	AZ1 EMERGENCY	*	*	*	_____
AZ #2 EMERGENCY	AZ2 EMERGENCY	*	*	*	_____
EL EMERGENCY	EL EMERGENCY	*	*	*	_____
DISH DOOR EMERGENCY	DISH DOOR EMER	*	*	*	_____
INPUT BREAKER	3 PHASE PWR LOSS	*	*	*	_____
AZ HANDCRANK	AZ HANDCRANK	*	*		_____
AZ BRAKE INTERLOCK	AZ BRAKE INTERLK	*	*		_____
AZ BRAKE FAULT	AZ BRAKE FAULT	*			_____
LOW ANGLE	LOW ANGLE	*			_____
EL HANDCRANK	EL HANDCRANK	*		*	_____
EL BRAKE INTERLOCK	EL BRAKE INTERLK	*		*	_____
EL BRAKE FAULT	EL BRAKE FAULT	*			_____
AZ #1 FIELD CURRENT OR CB	AZ1 FIELD FAULT	*			_____
AZ #2 FIELD CURRENT OR CB	AZ2 FIELD FAULT	*			_____
AZ #1 ARMATURE CB	AZ1 MTR CONTROL	*			_____
AZ #2 ARMATURE CB	AZ2 MTR CONTROL	*			_____
AZ #1 ELECTRONICS CB	AZ1 MTR CONTROL	*			_____
AZ #2 ELECTRONICS CB	AZ2 MTR CONTROL	*			_____
AZ #1 MOTOR THERMOSTAT	AZ1 MTR OVERTEMP	*			_____
AZ #2 MOTOR THERMOSTAT	AZ2 MTR OVERTEMP	*			_____
AZ #1 BLOWER CB	AZ BLOWER CB	*			_____
AZ #2 BLOWER CB	AZ BLOWER CB	*			_____
EL FIELD CURRENT OR CB	EL FIELD FAULT	*		*	_____
EL ARMATURE CB	EL1 MTR CONTROL	*		*	_____
EL ELECTRONICS CB	EL1 MTR CONTROL	*		*	_____
EL MOTOR THERMOSTAT	EL MTR OVERTEMP	*		*	_____
EL BLOWER CB	EL BLOWER CB	*			_____

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4.1.3 Current Fault Status

4.1.3.1 Disable AZ Motor #2 assembly using Armature CB. With ACU in Manual mode zero rate command inject a 2.7 volt signal at A1 (A6) BJ2-24. (Open BJ2-24 and inject 2.7 volt at C20-4). Note within 10 seconds an axis shut down with a current fault being reported for AZ(EL) #1 Motor. Message should read AZ1 CURRENT FAULT (EL CURRENT FAULT).
AZ ____ (EL) ____ (CHECK)

4.1.3.2 Clear the current fault by depressing the axis disable switch on the ACU and re-enable Motor #2 Armature CB. Disable Motor #1 assembly and repeat 4.1.3.1 for AZ #2 Motor looking for an AZ 2 Current Fault. (Open BJ2-25 and inject 2.7 volt at C28-3.) Re-enable Motor #1 assembly and clear the current fault by depressing the axis disable switch on the ACU. ____ (CHECK)

4.2 TRAVEL LIMIT TEST

4.2.1 Azimuth CW

4.2.1.1 Drive the azimuth axis CW and record the angle at which the azimuth PRELIMIT interlock is tripped.
ANGLE ____ (RECORD)
Message "AZ CW PRELIMIT" ____ (CHECK)

4.2.1.2 Verify that the antenna will drive in a CCW direction at a slow rate while the MANUAL rate button is being pushed until the PRELIMIT is cleared. ____ (CHECK)

4.2.1.3 Defeat the PRELIMIT interlock and continue to drive the azimuth axis CW. Record the angle at which the FINAL LIMIT interlock is tripped. .
ANGLE ____ (RECORD)
Message "AZ CW LIMIT" ____ (CHECK)

4.2.1.4 Verify that the azimuth drives are disabled. ____ (CHECK)
Use handcranks to drive out of the limit area. Restore PRELIMIT interlock.

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4.2.2 Azimuth CCW

4.2.2.1 Drive the azimuth axis CCW and record the angle at which the azimuth PRE-LIMIT interlock is tripped.

ANGLE _____ (RECORD)

Message "AZ CCW PRELIMIT" _____ (CHECK)

4.2.2.2 Verify that the antenna drives in a CW direction at a slow rate while the MANUAL rate button is being pushed until the prelimit is cleared. _____ (CHECK)

4.2.2.3 Defeat the PRELIMIT interlock and continue to drive the azimuth axis CCW and record that angle at which the FINAL LIMIT interlock is tripped.

ANGLE _____ (RECORD)

Message "AZ CCW LIMIT" _____ (CHECK)

4.2.2.4 Verify that the azimuth drives are disabled. _____ (CHECK)

Use handcranks to drive out of limit area. Restore PRELIMIT interlock.

4.2.3 Elevation Up

4.2.3.1 Drive the elevation axis UP and record the angle at which the elevation PRELIMIT interlock is tripped.

ANGLE _____ (RECORD)

Message "EL UP PRELIMIT" _____ (CHECK)

4.2.3.2 Verify that the antenna drives in a DOWN direction at a slow rate while the MANUAL rate button is being pushed until the prelimit is cleared. _____ (CHECK)

4.2.3.3 Defeat the PRELIMIT interlock and continue to drive the elevation axis UP. Record the angle at which the FINAL LIMIT indicator is tripped.

ANGLE _____ (RECORD)

Message "EL UP LIMIT" _____ (CHECK)

4.2.3.4 Verify that the elevation drives are disabled. Use handcranks to drive out of limit area. Restore PRELIMIT interlock. _____ (CHECK)

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4.2.4 Elevation Down

4.2.4.1 Drive the elevation axis DOWN and record the angle at which the elevation PRELIMIT interlock is tripped.

ANGLE _____ (RECORD)

Message "EL DOWN PRELIMIT" _____ (CHECK)

4.2.4.2 Verify that the antenna drives in the UP direction at a slow rate while the MANUAL rate button is being pushed until the limit is cleared. _____ (CHECK)

4.2.4.3 Defeat the PRELIMIT interlock and continue to drive the elevation axis DOWN. Record the angle at which the FINAL LIMIT indicator is tripped.

ANGLE _____ (RECORD)

Message "EL DOWN LIMIT" _____ (CHECK)

4.2.4.4 Verify that the elevation drives are disabled. _____ (CHECK)

4.2.4.5 Use handcranks to drive out of limit area. Restore PRELIMIT interlock.

4.3 MANUAL MODES TEST

4.3.1 Manual Enable

4.3.1.1 Select the MANUAL ENABLE mode and verify that the speed and direction of antenna movement can be controlled by the rate controls on the ACU.

AZ _____ (EL) _____ (CHECK)

4.3.1.2 Command a full velocity for each direction of each axis and record the angle through which the axis travels during a one-minute interval:

AZ CW _____ (RECORD)

AZ CCW _____ (RECORD)

EL UP _____ (RECORD)

EL DN _____ (RECORD)

4.3.1.3 Calculate velocity in degrees per second:

AZ CW _____ (RECORD)

AZ CCW _____ (RECORD)

EL UP _____ (RECORD)

EL DN _____ (RECORD)

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4.3.2 SLEW Enable

4.3.2.1 Select the SLEW ENABLE mode and verify that the speed and direction of antenna movement can be controlled by the rate controls on the ACU.

AZ ____ (EL) ____ (CHECK)

4.3.2.2 Command a full velocity for each direction of each axis and record the angle through which the axis travels during a one-minute interval:

AZ CW ____ (RECORD)

AZ CCW ____ (RECORD)

EL UP ____ (RECORD)

EL DN ____ (RECORD)

4.3.2.3 Calculate velocity in degrees per second:

AZ CW ____ (RECORD)

AZ CCW ____ (RECORD)

EL UP ____ (RECORD)

EL DN ____ (RECORD)

4.3.3 Monitor Test

4.3.3.1 Select SLEW ENABLE mode and place command at zero. Enable the monitor by pressing MONITOR.

MONITOR illuminates green ____ (CHECK)

4.3.3.2 Give a full CW (UP) command. The monitor circuit should cause the mode to revert to STANDBY within 1.0 seconds.

Reverts within limit. AZ ____ (EL) ____ (CHECK)

Monitor is red. AZ ____ (EL) ____ (CHECK)

NOTE: MONITOR TIME constant switch must be in position 4.

4.3.3.3 Return command to zero and reset monitor. Repeat for CCW (DN) command.

Reverts within limit. AZ ____ (EL) ____ (CHECK)

Monitor is red. AZ ____ (EL) ____ (CHECK)

4.3.4 Remote Control Box

4.3.4.1 Connect the remote control box at the drive cabinet. Verify that control of the antenna is not possible until the ACU is in REMOTE mode. ____ (CHECK)

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4.3.4.2 With ACU in REMOTE mode, verify that the speed and direction of antenna movement can be controlled from the remote control box.

AZ ____ (EL) ____ (CHECK)

4.3.4.3 Repeat paragraphs 4.3.4.1 and 4.3.4.2 with the remote control box connected at the portable control junction box.

4.3.4.1 ____ (CHECK)

4.3.4.2 AZ ____ (EL) ____ (CHECK)

4.4 AUTO MODES TEST

4.4.1 Manual Position

4.4.1.1 Select MANUAL POSITION mode at the ACU. Verify that speed and direction of antenna movement can be controlled by the ACU rate controls.

AZ ____ (EL) ____ (CHECK)

4.4.1.2 Set command to zero, record position and verify that there is no more than 0.01 degrees of drift over a two minute period.

AZ ____ degrees (RECORD)

EL ____ degrees (RECORD)

No drift.

AZ ____ (EL) ____ (CHECK)

4.4.2 20 Satellite Positions

4.4.2.1 Put DATA section of display into DISPLAY KEYBOARD mode. Store a command position for Satellite 1 Azimuth and Satellite 1 Elevation. Record below.

S01 AZ ____ degrees (RECORD)

S01 EL ____ degrees (RECORD)

4.4.2.2 Place the ACU in SAT 1 mode. The system should drive to the stored command position. Record position after the system settles. Actual position should equal command position ± 0.01 degrees.

Azimuth Actual ____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg ____ degrees (CHECK)

Elevation Actual ____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg ____ degrees (CHECK)

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4.4.2.3 Repeat paragraphs 4.4.2.1 and 4.4.2.2 for Satellite 2 positions.

S02 AZ _____ degrees (RECORD)

S02 EL _____ degrees (RECORD)

Azimuth Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

Elevation Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

4.4.2.4 Repeat paragraphs 4.4.2.1 and 4.4.2.2 for Satellite 3 positions.

S03 AZ _____ degrees (RECORD)

S03 EL _____ degrees (RECORD)

Azimuth Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

Elevation Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

4.4.2.5 Repeat paragraphs 4.4.2.1 and 4.4.2.2 for Satellite 4 positions.

S04 AZ _____ degrees (RECORD)

S04 EL _____ degrees (RECORD)

Azimuth Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

Elevation Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

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4.4.2.6 Repeat paragraphs 4.4.2.1 and 4.4.2.2 for Satellite 5 positions.

S05 AZ _____ degrees (RECORD)

S05 EL _____ degrees (RECORD)

Azimuth Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

Elevation Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

4.4.2.7 Repeat paragraphs 4.4.2.1 and 4.4.2.2 for Satellite 6 positions.

S06 AZ _____ degrees (RECORD)

S06 EL _____ degrees (RECORD)

Azimuth Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

Elevation Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

4.4.2.8 Repeat paragraphs 4.4.2.1 and 4.4.2.2 for Satellite 7 positions.

S07 AZ _____ degrees (RECORD)

S07 EL _____ degrees (RECORD)

Azimuth Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

Elevation Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

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4.4.2.9 Repeat paragraphs 4.4.2.1 and 4.4.2.2 for Satellite 8 positions.

S08 AZ _____ degrees (RECORD)

S08 EL _____ degrees (RECORD)

Azimuth Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

Elevation Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

4.4.2.10 Repeat paragraphs 4.4.2.1 and 4.4.2.2 for Satellite 9 positions.

S09 AZ _____ degrees (RECORD)

S09 EL _____ degrees (RECORD)

Azimuth Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

Elevation Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

4.4.2.11 Repeat paragraphs 4.4.2.1 and 4.4.2.2 for Satellite 10 positions.

S10 AZ _____ degrees (RECORD)

S10 EL _____ degrees (RECORD)

Azimuth Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

Elevation Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

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4.4.2.12 Repeat paragraphs 4.4.2.1 and 4.4.2.2 for Satellite 11 positions.

S11 AZ _____ degrees (RECORD)

S11 EL _____ degrees (RECORD)

Azimuth Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

Elevation Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

4.4.2.13 Repeat paragraphs 4.4.2.1 and 4.4.2.2 for Satellite 12 positions.

S12 AZ _____ degrees (RECORD)

S12 EL _____ degrees (RECORD)

Azimuth Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

Elevation Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

4.4.2.14 Repeat paragraphs 4.4.2.1 and 4.4.2.2 for Satellite 13 positions.

S13 AZ _____ degrees (RECORD)

S13 EL _____ degrees (RECORD)

Azimuth Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

Elevation Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

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4.4.2.15 Repeat paragraphs 4.4.2.1 and 4.4.2.2 for Satellite 14 positions.

S14 AZ _____ degrees (RECORD)

S14 EL _____ degrees (RECORD)

Azimuth Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

Elevation Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

4.4.2.16 Repeat paragraphs 4.4.2.1 and 4.4.2.2 for Satellite 15 positions.

S15 AZ _____ degrees (RECORD)

S15 EL _____ degrees (RECORD)

Azimuth Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

Elevation Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

4.4.2.17 Repeat paragraphs 4.4.2.1 and 4.4.2.2 for Satellite 16 positions.

S16 AZ _____ degrees (RECORD)

S16 EL _____ degrees (RECORD)

Azimuth Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

Elevation Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

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4.4.2.18 Repeat paragraphs 4.4.2.1 and 4.4.2.2 for Satellite 17 positions.

S17 AZ _____ degrees (RECORD)

S17 EL _____ degrees (RECORD)

Azimuth Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

Elevation Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

4.4.2.19 Repeat paragraphs 4.4.2.1 and 4.4.2.2 for Satellite 18 positions.

S18 AZ _____ degrees (RECORD)

S18 EL _____ degrees (RECORD)

Azimuth Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

Elevation Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

4.4.2.20 Repeat paragraphs 4.4.2.1 and 4.4.2.2 for Satellite 19 positions.

S19 AZ _____ degrees (RECORD)

S19 EL _____ degrees (RECORD)

Azimuth Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

Elevation Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

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4.4.2.21 Repeat paragraphs 4.4.2.1 and 4.4.2.2 for Satellite 20 positions.

S20 AZ _____ degrees (RECORD)

S20 EL _____ degrees (RECORD)

Azimuth Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

Elevation Actual _____ degrees (RECORD)

[Actual - Command] \leq 0.01 deg _____ degrees (CHECK)

4.4.2.22 Place ACU in STANDBY mode.

4.5 SYSTEM RESPONSE TEST

4.5.1 Rate Loop Tests

4.5.1.1 Set-up

4.5.1.1.1 Remove the rate command from the input to the rate loop and replace with a function generator.

AZ _____ (EL) _____ (CHECK)

4.5.1.1.2 Monitor the output of the function generator with one channel of the chart recorder and tachometer rate feedback A1A1B17-7 with the other.

AZ _____ (EL) _____ (CHECK)

4.5.1.1.3 Place system in MANUAL ENABLE.

AZ _____ (EL) _____ (CHECK)

4.5.1.2 Minimum Smooth Velocity

4.5.1.2.1 Calibrate chart recorder so that .02 deg/sec equals full scale on both channels.

AZ _____ (EL) _____ (CHECK)

4.5.1.2.2 Set function generator to generate a .1 Hz triangular wave with zero DC offset.

AZ _____ (EL) _____ (CHECK)

4.5.1.2.3 Adjust amplitude of triangular wave for a peak of .02 deg/sec.

AZ _____ (EL) _____ (CHECK)

4.5.1.2.4 Record several cycles of the COMMAND and TACH voltages on the chart recorder.

AZ _____ (EL) _____ (CHECK)

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- 4.5.1.2.5 Note point at which antenna velocity drops to zero as seen by the recorded TACH voltage. Record below. It should be less than .01 deg/sec.

AZIMUTH CW _____ degrees/second (RECORD)

AZIMUTH CCW _____ degrees/second (RECORD)

ELEVATION UP _____ degrees/second (RECORD)

ELEVATION DN _____ degrees/second (RECORD)

4.5.1.3 Small Signal Step Response

- 4.5.1.3.1 Select the square wave output of the function generator and adjust the amplitude for 1 volt peak to peak at .2 Hz.

AZ _____ (EL) _____ (CHECK)

- 4.5.1.3.2 Record several cycles of the COMMAND and TACH voltages on the chart recorder.

AZ _____ (EL) _____ (CHECK)

- 4.5.1.3.3 Record overshoot.

AZ _____ percent (RECORD)

(EL) _____ percent (RECORD)

4.5.1.4 Large Signal Step Response

- 4.5.1.4.1 Adjust the amplitude of the function generator output to 10 volts peak to peak.

AZ _____ (EL) _____ (CHECK)

- 4.5.1.4.2 Record several cycles of the COMMAND and TACH voltages on the chart recorder.

AZ _____ (EL) _____ (CHECK)

- 4.5.1.4.3 Record Overshoot.

AZ _____ \leq 25 percent (RECORD)

(EL) _____ \leq 25 percent (RECORD)

4.5.1.5 Acceleration

Using the above recordings, measure the maximum slope of the TACH feedback and calculate acceleration.

4.5.1.6 Rate Loop Bandwidth and Locked Rotor Resonance

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- 4.5.1.6.1 Set the sine wave output of the function generator to 1 volt peak to peak. With the chart recorder running, slowly sweep the frequency of the function generator upward (making sure the output of the function generator remains constant) until the system no longer responds as indicated by the chart recording.

CAUTION

AN OBSERVER SHOULD BE PLACED NEAR THE ANTENNA
READY TO DISABLE THE DRIVE AS THE FUNCTION GEN-
ERATOR PASSES THROUGH THE RESONANT FREQUENCY OF
THE ANTENNA, IF DAMAGE TO THE ANTENNA SEEMS LIKELY.

- 4.5.1.6.2 From the above recording, determine the frequency at which the output voltage from the TACH has decreased 3 dB.

Azimuth Rate Loop Bandwidth _____ (RECORD)

Elevation Rate Loop Bandwidth _____ (RECORD)

- 4.5.1.6.3 From the above recording, determine the Locked Rotor Resonance by looking for a definable null of the TACH voltage.

Azimuth Locked Rotor Resonance _____ (RECORD)

Elevation Locked Rotor Resonance _____ (RECORD)

- 4.5.1.6.4 Place system in STANDBY and disconnect the function generator and chart recorder.

AZ _____ (EL) _____ (CHECK)

- 4.5.1.6.5 Restore the rate command connection.

AZ _____ (EL) _____ (CHECK)

4.5.2 Position Loop Test

4.5.2.1 Set-Up

- 4.5.2.1.1 The ESI Position Test Set is used for this group of tests. Connect the eight least significant bits of each axis to the test set.

_____ (CHECK)

- 4.5.2.1.2 Connect each output of the test set to a channel on the chart recorder.

_____ (CHECK)

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4.5.2.2 Large Signal Step Response

- 4.5.2.2.1 Place coordinates for Satellite 1 and Satellite 2 into the system that will cause a 1 degree step to be applied to each axis when changing between them.

S01 AZ _____ EL _____ (RECORD)

S02 AZ _____ EL _____ (RECORD)

- 4.5.2.2.2 Position antenna to Satellite 1 coordinates, then select Satellite 2 and record position response on chart recorder. Switch between Satellite 1 and Satellite 2 several times and record on chart recorder. _____ (CHECK)

- 4.5.2.2.3 System should settle within 1-1/2 cycles and have less than 25 percent overshoot. Overdamped response is acceptable. _____ (CHECK)

4.5.2.3 Position Loop Bandwidth

- 4.5.2.3.1 Perform this test on Azimuth first then on Elevation. Set the STC Parameter to 255. _____ (CHECK)

- 4.5.2.3.2 Connect the function generator through a 1 megohm resistor to U22-8 for Azimuth and U26-8 for Elevation of the AUTO CONTROL CARD (A2) of the DACU. AZ _____ (EL) _____ (CHECK)

- 4.5.2.3.3 Connect the output of the test set for the axis under test to one channel of the chart recorder and the function generator to the other channel. AZ _____ (EL) _____ (CHECK)

- 4.5.2.3.4 Select a .01 Hz sine wave from the function generator and set amplitude to zero. AZ _____ (EL) _____ (CHECK)

- 4.5.2.3.5 Place the system in MANUAL POSITION mode in position hold and slowly increase amplitude of the sine wave until a .02 degree peak to peak movement of the antenna is seen. [For increased resolution beyond that of the readouts the Azimuth POSITION ERROR (R9-R7) and Elevation POSITION ERROR (R12-R10) registers can be called up on the DACU.]

- 4.5.2.3.6 Calibrate the test set for an approximate full scale deflection of the chart recorder. AZ _____ (EL) _____ (CHECK)

- 4.5.2.3.7 With the chart recorder running, slowly sweep the frequency of the function generator upward (making sure the output of the function generator remains constant) until system no longer responds as indicated by the chart recording.

AZ _____ (EL) _____ (CHECK)

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4.6

Parameter Record

Configure the system for normal operation. Record the following parameters.

AES _____	BA3 _____	ESF _____
AOS _____	B03 _____	ESR _____
ASF _____	C01 _____	ETA _____
ASR _____	CA1 _____	ETO _____
ATO _____	C02 _____	PSA _____
ATA _____	CA2 _____	PSO _____
BA1 _____	C03 _____	SAS _____
B01 _____	CA3 _____	SOS _____
BA2 _____	EES _____	STC _____
B02 _____	EOS _____	SRC _____

NOTE: ASF (ESF) must be entered before AOS (EOS).

END OF TEST



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COMMENTS

WITNESS _____

DATE _____

FOR _____

WITNESS _____

DATE _____

FOR _____

WITNESS _____

DATE _____

FOR ELECTROSPACE SYSTEMS, INC. _____

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